

# Contract Scheduling with Distributional and Multiple Advice

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# Algorithm with predictions example: binary search

$n$  elements

8	11	14	16	18	25	30	36	40	43	46	49	50	53	54	56	59	60	63
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$$q = 16$$

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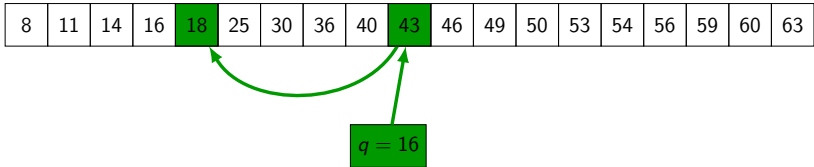
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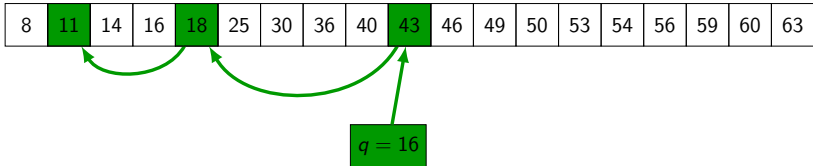
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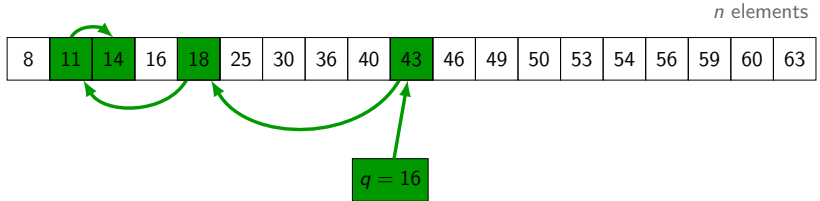


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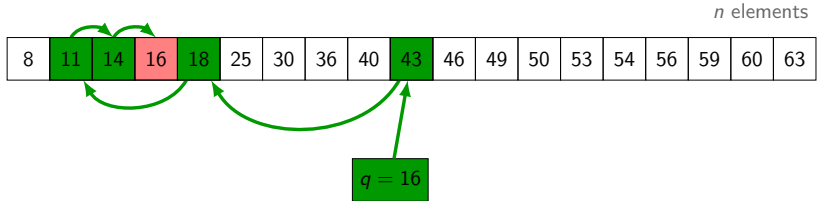
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Prediction: position  $h(q)$

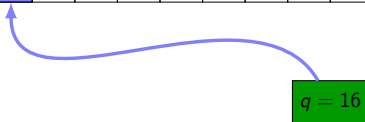
Error:  $\eta = |h(q) - \text{index}(q)|$



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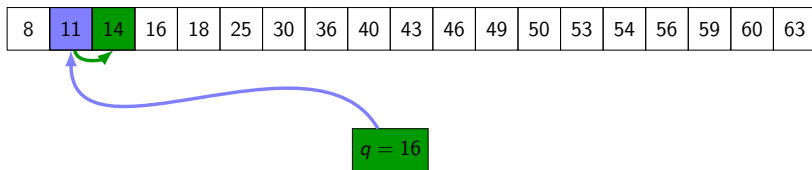


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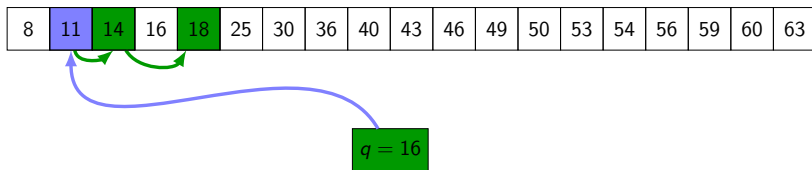


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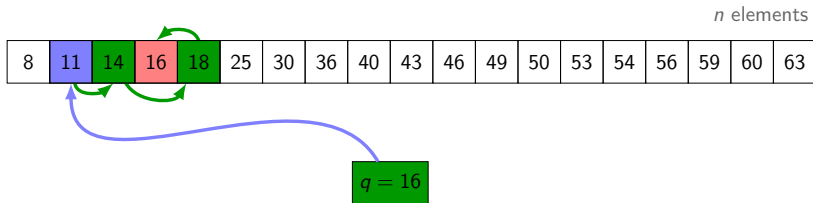
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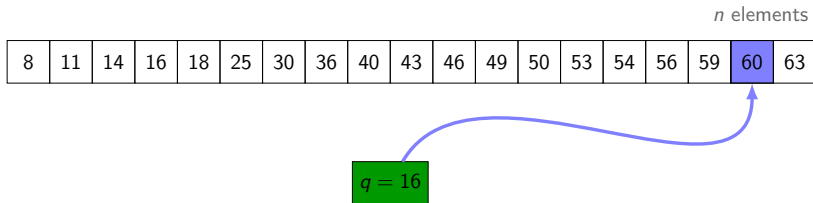
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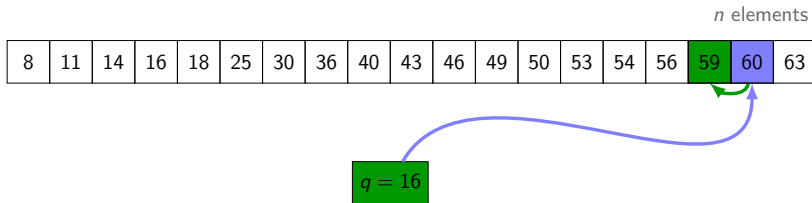
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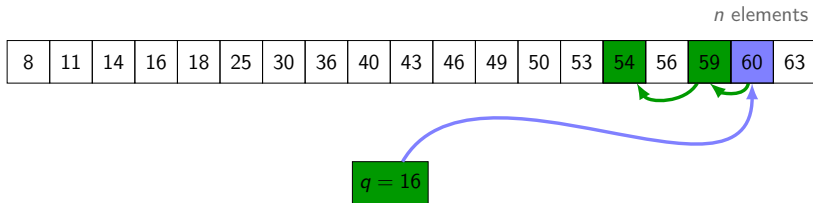
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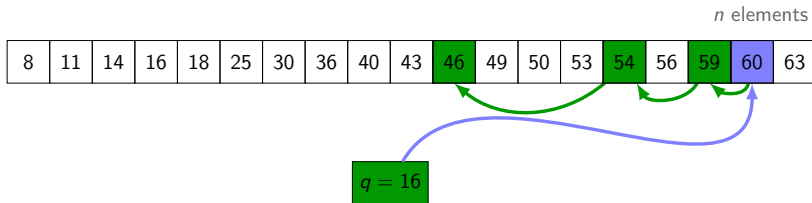
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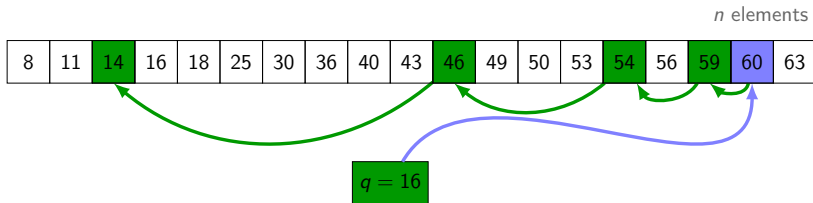


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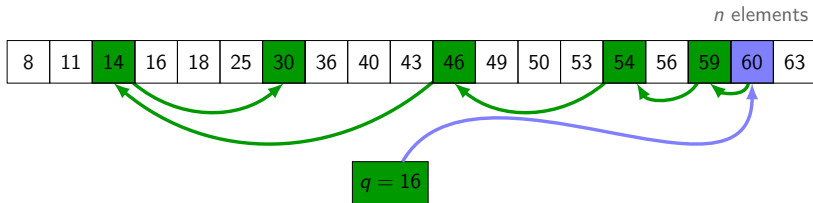
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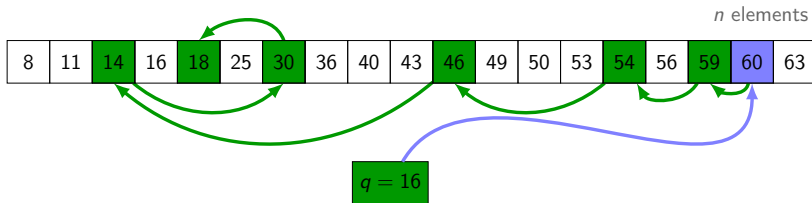
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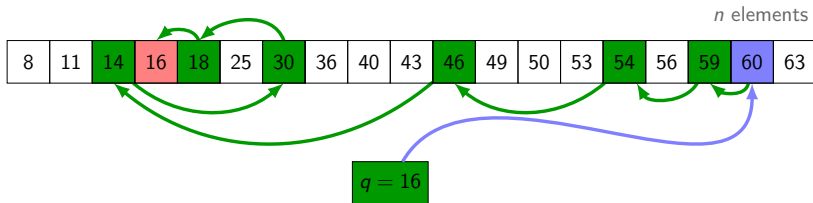
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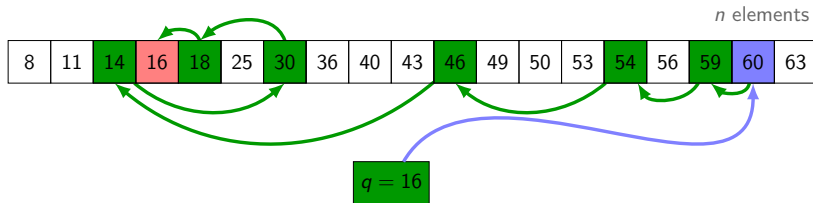
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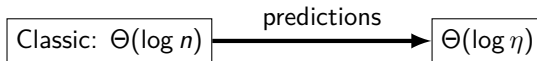
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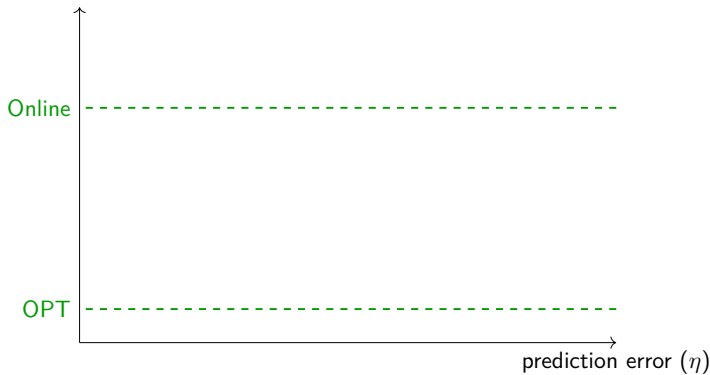
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Practical applications [KraskaBCDP '18]

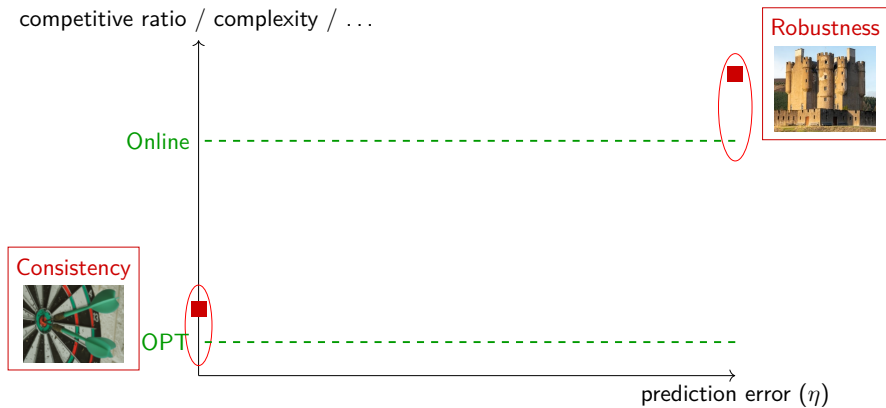
# Properties we seek

competitive ratio / complexity / ...



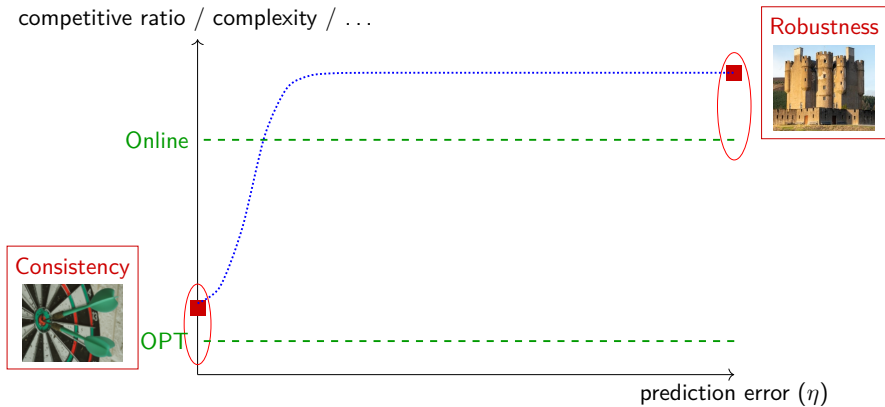
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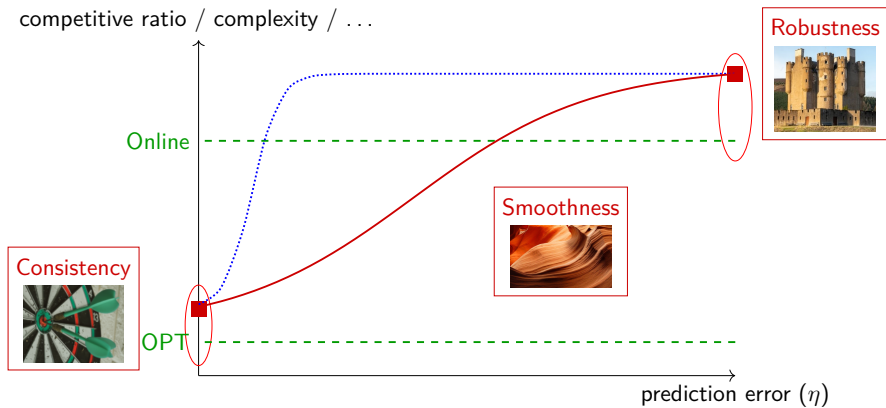
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# Contract algorithms & contract scheduling

## Contract algorithms

- ▶ Inputs include allowed processing time
- ▶ Performance improves if more time is allotted

## Contract scheduling

- ▶ contract algorithm  $\Rightarrow$  *anytime* algorithm  
(*anytime* = can get interrupted “any time” and outputs a solution)

1s	3s	6s	
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Example: interruption at 8s, largest contract executed = 3s

# Acceleration ratio

## Schedule definition

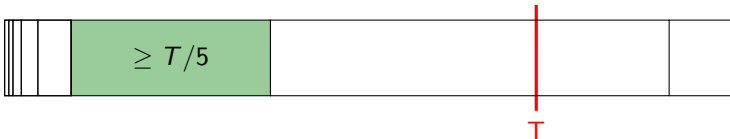
- ▶ sequence  $\mathbf{X} = \{x_i\}_{i \in \mathbb{Z}}$ ,  $x_i = i$ th execution length
- ▶ start at  $-\infty$  so that no interruption happens before 1st execution
- ▶ performance of  $\mathbf{X}$  if interruption at  $T$ :  $\ell(\mathbf{X}, T)$   
(length of the last contract terminated by  $\mathbf{X}$  at time  $T$ )

## Quality of a schedule

- ▶ acceleration ratio:

$$\text{acc}(\mathbf{X}) = \sup_T \frac{T}{\ell(\mathbf{X}, T)}$$

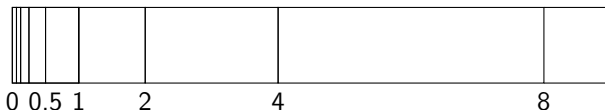
e.g.,  $\text{acc}(\mathbf{X}) = 5 \Rightarrow \forall T$ , a contract has run for  $\geq T/5$



# Classic (no prediction) problem

Best contract algorithms:  $X(\lambda)$  with  $x_i = 2^{i+\lambda}$  for any  $\lambda \in [0, 1]$

Example with  $\lambda = 0$ :



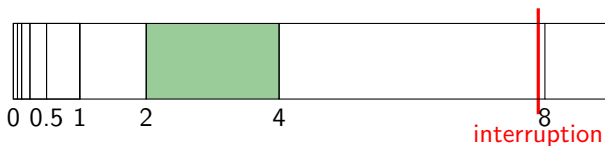
Proposition (from [Russel Zimberstein 91, Alpern Gal 03])

*The acceleration ratio of  $X(\lambda)$  is 4. All other algorithms are worse.*

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# Previous work on single predictions

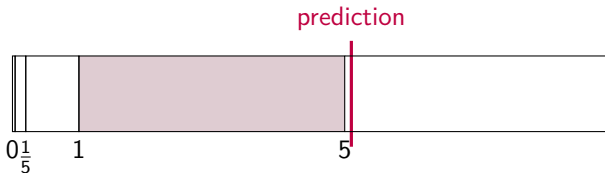
[AK'23]

## Framework

- ▶ prediction  $p$  = interruption time

## Approach

- ▶ fix target robustness  $r$ , restrict to geometrical solutions.  
Candidate schedules are  $\{a^{i+\lambda}\}_{i \in \mathbb{Z}}$  with  $a \in \left[\frac{1}{2}(r \pm \sqrt{r^2 - 4r})\right]$
- ▶ best solution: largest  $a$ , shift  $\lambda$  to “aim” at  $p$
- ▶ issue: not smooth  
explore prediction with bounded error



# Outline

- 1 Introduction
- 2 Distributional predictions**
- 3 Multiple advice
- 4 Numerical observations



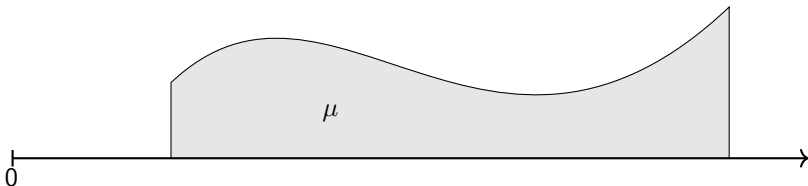
# Distributional predictions

## Framework

- ▶ prediction  $\mu$  = prob. distr. of the interruption time
- ▶ to simplify: aim at best consistency while staying 4-robust  
only choice:  $\lambda \in [0, 1]$  in  $\{2^{i+\lambda}\}_{i \in \mathbb{Z}}$

## Consistency definition

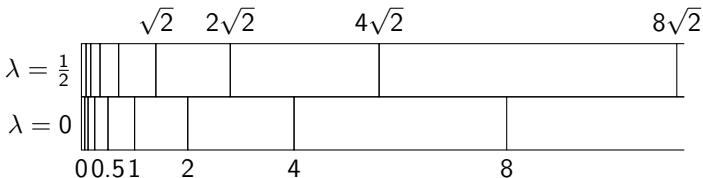
$$c(X, \mu) = \frac{\mathbb{E}_{T \sim \mu}[T]}{\mathbb{E}_{T \sim \mu}[\ell(X, T)]}$$



# Can we do something without any assumption on $\mu$ ?

## First idea

- ▶ take two opposite shifted schedules  $\{2^{i+\lambda}\}_{i \in \mathbb{Z}} : (\lambda \in \{0, \frac{1}{2}\})$ , select “the best”
- ▶  $\Rightarrow 8(\sqrt{2} - 1)$  - consistent



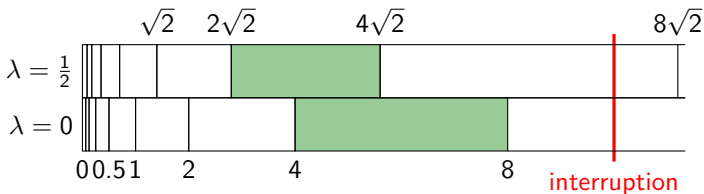
## Best of $n$ regularly shifted schedules

- ▶  $\Rightarrow 4n(2^{-1/n} - 1)$  - consistent
- ▶  $\longrightarrow_{n \rightarrow \infty} 4 \ln 2$

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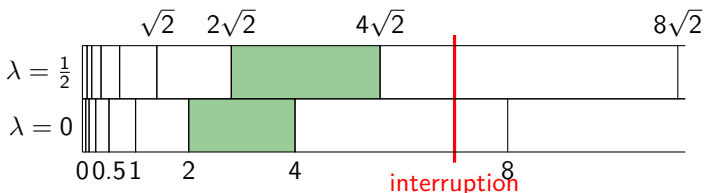
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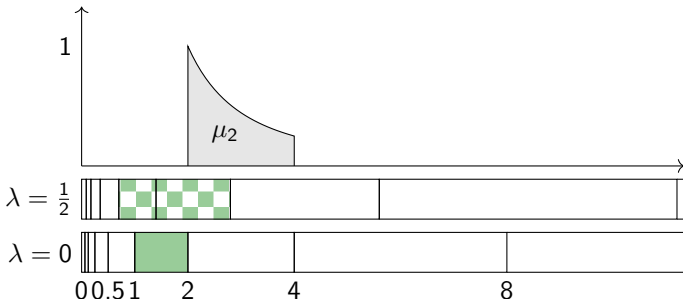
# Distributional lower bound

## Summary

- ▶ the previous solutions are tight

### Theorem

*For any  $D$  and  $\mu_D$  having a density  $f_D(x) = \frac{2D}{x^2}$  on  $[D; 2D]$ , no 4-robust schedule has a consistency better than  $4 \ln 2$ .*



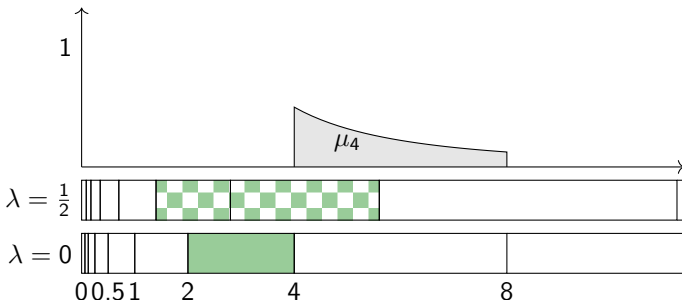
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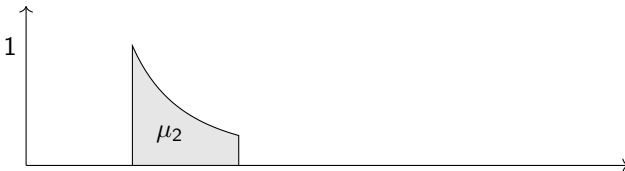
# “Smoothness”

## Recall on single predictions

- ▶ best algorithm:  $\varepsilon$  error on prediction destroys everything

## On distributed predictions

- ▶ intuitively: worst-case predictions needs *balanced* probability mass  
small perturbation  $\Rightarrow$  small impact on performance  
same worst-case for all 4-robust schedules
- ▶ formally: perturbation measured via [Earth-Mover Distance](#)
- ▶ technical result: if the actual distribution is close to  $\mu_D$  (wrt EMD),  
then the acceleration ratio of any 4-robust schedule is close to  $4 \ln 2$



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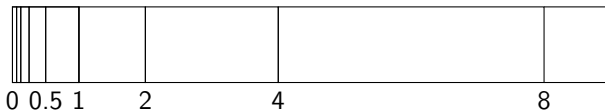
# Prediction = multiple advice

## Framework

- ▶ prediction  $P = \{\tau_1, \dots, \tau_k\}$
- ▶ goal: optimize performance wrt adversarial interruption among  $P$

## Consistency definition

- ▶  $c(X, P) = \sup_{\tau \in P} \frac{\tau}{\ell(X, \tau)}$



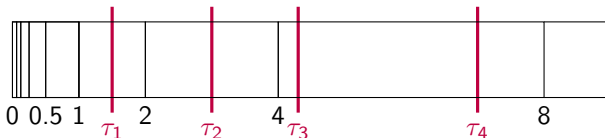
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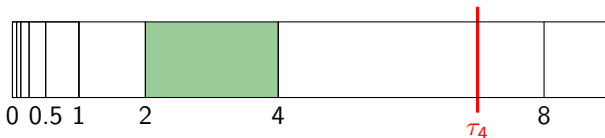
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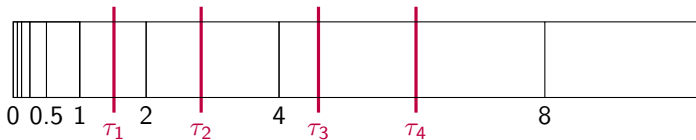
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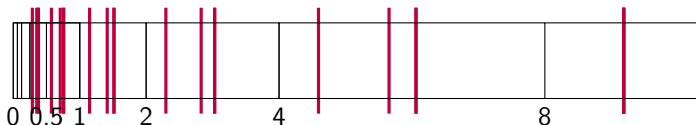
# Algorithm



$$\tau_j = 2^{i_j + \lambda_j}, \text{ such that } i_j \in \mathbb{Z}, \lambda_j \in [0, 1]$$

$$\text{ex} : \{\lambda_j\} = \{0.6, 0.5, 0.2, 0.6\}$$

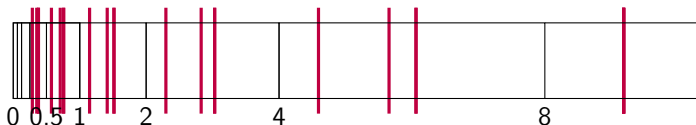
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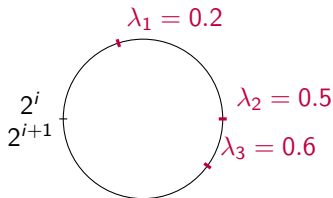
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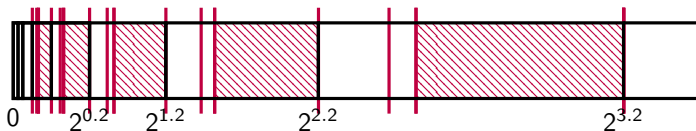


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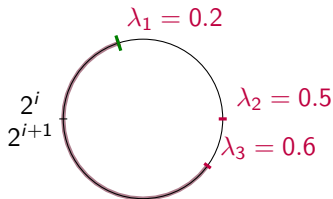


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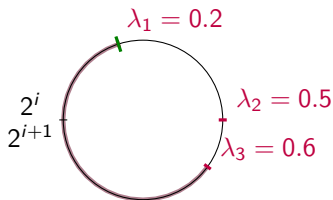
$$\Delta = \max_i (\lambda_{1+i \bmod k} - \lambda_i)$$

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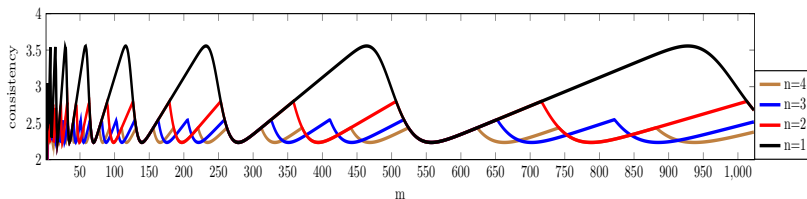
Consistency of choosing  $\lambda$  “targeting”  $\Delta$ :  $2^{2-\Delta} \geq 2^{2-\frac{1}{k}}$  (this is tight)



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# Distributional predictions



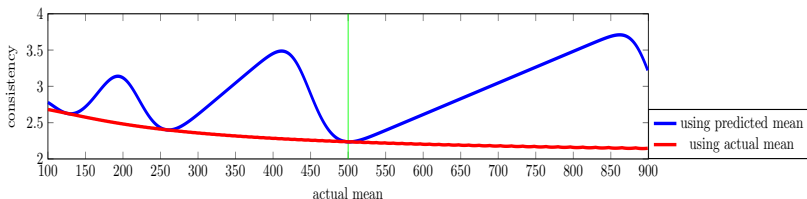
## Setup

- ▶ Algo: choose best among  $n$  schedules  $\{2^{i+k/n}\}_{i \in \mathbb{Z}}$  for  $k \in [1 \dots n]$
- ▶ Prediction: truncated normal distribution mean  $m$  st. dev.  $0.05m$
- ▶ Plot consistency in function of  $m$  (bottom is best)

## Remarks

- ▶ Larger  $n$  = minimum of more functions
- ▶ Steeper downward slope (worse to interrupt before a contract)

# Distributional predictions : “smoothness”



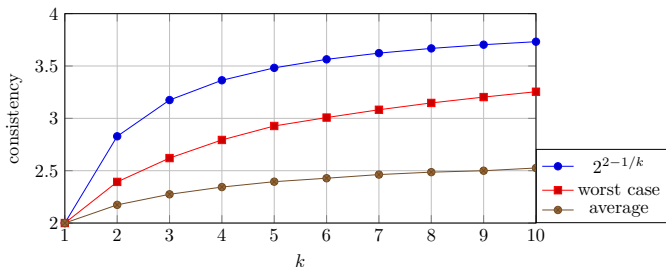
## Setup

- ▶ Algo: choose best among 16 schedules  $\{2^{i+k/n}\}_{i \in \mathbb{Z}}$  for  $k \in [1 \dots 16]$
- ▶ Prediction: - **Top curve**: truncated normal distribution mean 500,  $\sigma = 25$   
 - **Bottom curve**: truncated normal distribution mean  $m$ ,  $\sigma = 25$
- ▶ Interruption: truncated normal distribution mean  $m$ ,  $\sigma = 25$
- ▶ Plot ratio  $m$  over the expected performance

## Remarks

- ▶ Smooth asymmetric degradation with the error (linked to  $\sigma$ )

# Multiple predictions



## Setup

- ▶ Prediction  $P$ :  $k \in [1 \dots 10]$  candidate times drawn  $\mathcal{U}(1, 1024)$
- ▶ Plot: - theoretical consistency
  - experimental consistency, averaged over 1000 repetitions
  - experimental perf. if interruption drawn uniformly from  $P$

## Remarks

- ▶ Results with non-pathological predictions much better than theoretical bounds

# Conclusion

## Framework

- ▶ objective: study models beyond simple prediction
- ▶ original idea: prediction as probability distribution

## Results

- ▶ simple algorithms best consistency when robustness = 4
- ▶ hard to get more general results

## Future direction

- ▶ focus on a simpler related problem to aim at more general results:  
online bidding